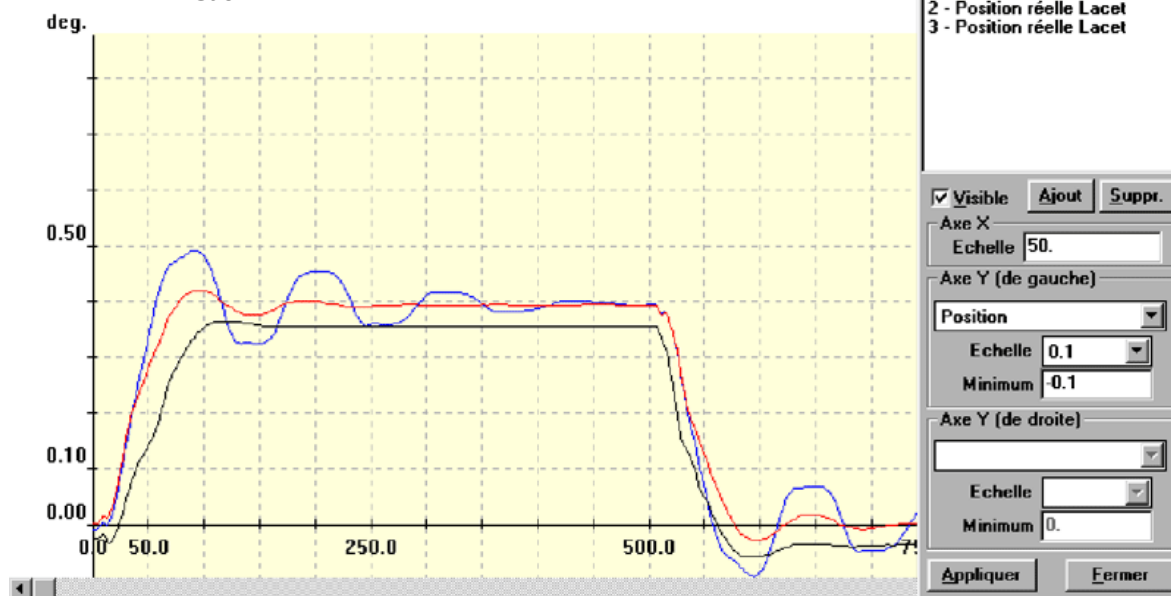


TP-PSI-CI5-04 – Robot ERICC3

Cas 1



Cas 2



Cas 3

